



Key Features

Stabilization Range

$\omega \pm 6^\circ$ (pitch)

Accuracy

$\phi \pm 6^\circ$ (roll)

$K \pm 30^\circ$ (yaw)

Payload

$\pm 0.2^\circ$ pitch/roll

Hole Diameter

$\pm 0.4^\circ$ yaw

Interface

20-85 kg

Voltage

<460mm

Power

3xRS232

Weight

22-34 VDC

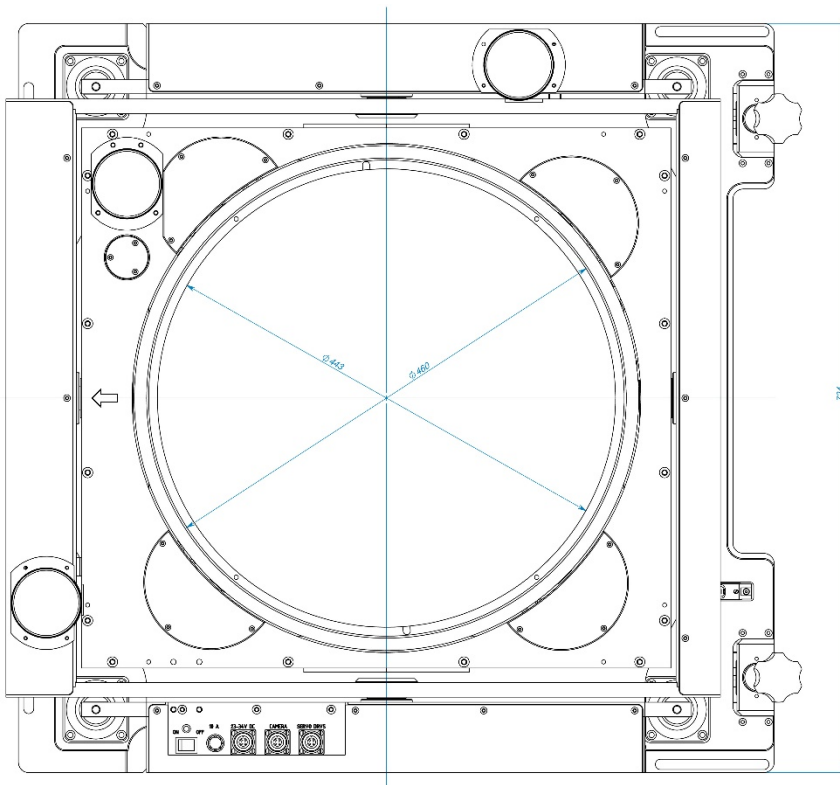
Dimensions

100 Watts (Peak)

75 Kg.

77x72x42cm

- Uses IMU data for most accurate stabilization
- Passive vibration shock absorbers to minimize high frequency vibrations
- Automatic crab angle compensation
- Independent servo drives



ASP-4 consisting of a kinematic design achieving unmatched accuracy in maintaining the camera system position relative to the flight line (pitch/roll/yaw).